# Triple Axis Servo Drive - TPD-M

### Overview

### Description

TPD-M is a multi axis system where each power module can supply up to three servo motors. The base configuration consists of a common DC bus supply (PSU) and multiples TPD-M modules, connected through DC bus bars.

The modules are available as one, two or three axis versions. This makes the system very flexible. The TPD-M drive has been specifically designed for the Packaging OEM market but it can also be used in many other centralized automation structures which incorporate a large number of servo axes offering significant advantages.

TPD-M controls also induction motors with feedback or sensorless in V/f mode.

- Packaging machines
- · Material forming machines
- Textile machines
- · Paper and converting lines
- · Plastics machines
- Machines tools

Motion control functionality is performed by means of EtherCAT Real Time CoE (CAN over Ethernet) communication, CAN / CANopen DS402 communication.

### **Features**

- The most compact multi-axis servo drive on the market
- · Quick and simple wiring
- One, two or three axis versions combined in one housing
- Removable SD card
- Common DC bus connection for energy exchange between drives
- Feedback: Resolver, Hiperface and EnDat interface, Hall sensors, rotary and linear encoders
- New feedback: Hiperface DSL feedback ® Reduced cabling; only one cable connection between drive & motor
- Fieldbus: CANopen standard, EtherCAT - option
- Serial link and CAN auto-address



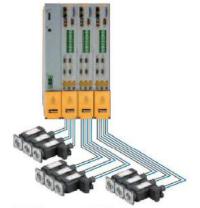
### Technical characteristics - Overview

TPD Axis	Continuos current [A <sub>rms</sub> ]	Peak current A (≤ 2 s)
0.44	2+2+2	4+4+4
3 axis	8 + 5 + 5	16 + 10 + 10
	2+2	4 + 4
0	5 + 5	10 + 10
2 axis	8 + 8	16 + 16
	15 + 5	30 + 10
1 axis	5/10/15/30	10/20/30/60

### **TPD-M Overview**

TPD-M has been developed for all applications where multiple drives are normally used and gives both OEMs and end users the opportunity to reduce build, configuration and operating costs, while boosting productivity and profitability.

Typical applications for TPD-M include packaging machines, material forming machines, textile, paper, converting and plastics machines, where large numbers of axes are required.



TPD-M system with Parker servo motors

#### **Features and Benefits**

#### Control cabinet space, size and cost savings

The integration of three servo power stages in a single housing offers machine builders the opportunity of having more compact control cabinets. Each TPD-M module is only 50 mm width (100 mm in the single axis 30 A version).

### Reduced system complexity

The complexity of the system is significantly reduced due to the following benefits:

- Fewer components (cables, connectors, filters and braking resistors)
- Fewer communication interconnections between devices
- · Centralized filtration and braking resistance

#### Reduce setup and maintenance costs

Due to the modular nature of TPD-M, machine design is much more straight forward. Additional axes can be added easily, simply by reproducing schemes from other existing axes. Programming time is reduced as only one drive unit needs to be configured.

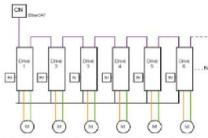
### Efficient power control

TPD-M works on a common DC bus power supply that allows the system to absorb and re-supply much of the braking energy to other TPD-M units rather than dissipating it in the form of heat via external resistors. In some instances, resistors can be removed completely and in others smaller resistors are required.

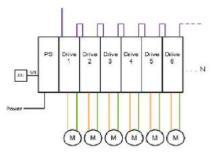
#### Standard Version

TPD-M servo drives is available as one, two or three axis versions. As standard TPD-M is supplied with:

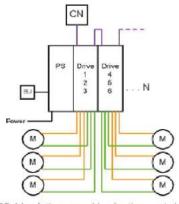
- CANopen
- · STO functionality
- · Digital and analog inputs/outputs
- Mechanical brake control



Traditional solution: one drive for each axis



Rack solution: one drive for each axes in a rack solution



TPD-M solution: one drive for three axis in a rack solution.Only one Power Supply

### **TPD-M Overview**

### Application

TPD-M servo drive is particularly suitable for all centralised automation systems, such as those found in many packaging machines, where large numbers of drives are often required.

- Packaging lines
- · Material forming machines
- Textile machines
- · Paper and converting lines
- · Plastics machines
- Machine tools



Additional features of TPD-M include an USB interface for configuration and setup plus a standard SD card interface for storing system parameters.

TPD-M can be integrated into a larger hybrid motion solution (centralized and decentralized) using Parker Motornet DC system.



#### **Options**

The capabilities of TPD-M can be further enhanced with numerous options which are available upon request, including:

- EtherCAT communication
- · Hiperface DSL® feedback
- Braking resistors
- · Additional inputs/outputs



#### Safety technology

TPD-M supports the "Safe Torque Off" (STO) safety function in the sense of the "Safe Stop", with protection against unexpected startup according to the requirements EN ISO 13849-1 Category 3. Together with the external safety control device, the "safe stop 1" (SS1) safety function according to the requirements of EN ISO 13849-1 category 3 can be used.

Switching off the motor torque must be effected by the machine controller.

According to a risk analysis which must be carried out according to the machine standard 89/392/EWG or EN 292; EN ISO 13849-1 and EN 1050, the machine manufacturer must project the safety system for the entire machine including all integrated components. This does also include the electrical drives.



## **Technical Characteristics**

### Technical Data

Туре		3 a	xis
AND	Unit	2 + 2 + 2	8 + 5 + 5
Rated Output Current	[A <sub>rms</sub> ]	2 + 2 + 2	8 + 5 + 5
Peak Output Current (≤ 2 s)	[A]	4 + 4 + 4	16 + 10 + 10
Maximum Continuous Module Output Current	[A]	6	<b>16</b> <sup>(1)</sup>
Maximum DC Voltage Supply		750	VDC

<sup>(1)</sup> The max continuous module current is clamped to 16 A

Туре			2 a	xis			1 a	ixis	ĺ
	Unit	2+2	5 + 5	8+8	5 + 15	5	10	15	30
Rated Output Current	[A <sub>rms</sub> ]	2+2	5 + 5	8+8	5 + 15	5	10	15	30
Peak Output Current (≤ 2 s)	[A]	4 + 4	10 + 10	16 + 16	10 + 30	10	20	30	60
Maximum Continuous Module Output Current	[A]	4	10	16	30	5	10	15	30
Maximum DC Voltage Supply					750	VDC			

### **PSUP - Power Supply Unit**

### Mains Supply

Power Supply Type	Unit		PSUP10			PSUP20			PSUP30	2)
Input Voltage				3	*230 480 (Rated)	VAC ±10 voltage 3*4		Hz		
Output Voltage					325	.680 VDC ±	:10 %			
Supplied Voltage	[VAC]	230	400	480	230	400	480	230	400	480
Output Power	[kVA]	6	10	10	12	20	20	18	30	30
Peak Output Power (<5 s)	[kVA]	12	20	20	24	40	40	34	60	60

### **Control Supply**

Rated Input Voltage			24 VDC ±10 %	
Maximum Ripple			1 V <sub>pkpk</sub>	
Supply Current	[A]	PSUP10D6: 0.2 A	PSUP20D6: 0.3 A	PSUP30D6: 0.3 A

<sup>(2)</sup> Operation of the PSUP30 only with line choke.

### **Environmental Characteristics**

Туре	TPD-M	PSUP
Operating Temperature	0+40 °C	
Storage Temperature	-25 °C+55	°C
Shipping Temperature	-25 °C+70	°C
Product Enclosure Rating	IP20 (only in closed electrical cabinet) UL open type equipment	
Altitude	1000 m ASL. Derate output current by 1.5 % pe	r 100 m to a maximum of 2000 m
Operating Humidity	Class 3K3 - Maximum 85 % non-condensing	
Storage Humidity	Class 1K3 - Maximum 95 % non-condensing	
Shipping Humidity	Class 2K3 - Maximum 95 % at 40 °C	
Operating Vibration	IEC60068-2-6 1057 Hz width 0.075 mm 57150 Hz accel. 9.81 m/s <sup>2</sup>	

### **TPD-M Features**

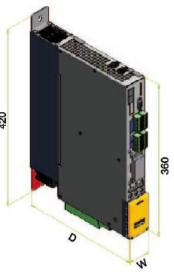
IFD-M reatures	
Communication	
	via USB port
Networks and Bus Systems	
	<ul> <li>CANopen, 201000kbit/s, SDO1, PDO1PDO4</li> </ul>
	EtherCAT, 100Mbit/s, 1 ms cycle time
	Via Gateway
	Profibus
	DeviceNet
Inputs / Outputs	
	4 digital input,
	2 digital output,
	1 analog input
	1 analog output for each axes.
	1 incremental encoder input,
	1 incremental encoder output
	Additional I/O
	3 analogue inputs 12bit,
	2 incremental encoder input,
	2 incremental encoder output
	Auxiliary Encoder
Supported Feedback	On USAMORIAN ALCOHOLI
	Resolver,
	SinCos,
	SinCos + EnDat,
	SinCos + Hiperface,
	SinCos (1 per pole pitch),
	Quadrature.
	Quadrature + Hall,
	• SinCos + Hall,
	Hiperface DSL®
Programming / Configuration	a PierPi C
	• PicoPLC
	MotionWiz with Oscilloscope function, real time and debugging features
	Removable SD card for
	• software upgrade,
	parameters and     application manners
Technology Functions	application memory
recimology i unctions	Torque control
	Speed control
	10 to \$100 to 10 t
	Position control
	Electronic gearbox
	Camming
Safety Functions	
	1 Safety Torque Off circuit for 3 axis module
	2 independent Safety Torque Off circuit for 2 axis module
	1 Safety Torque Off circuit for 1 axis module

### Standards & Conformance

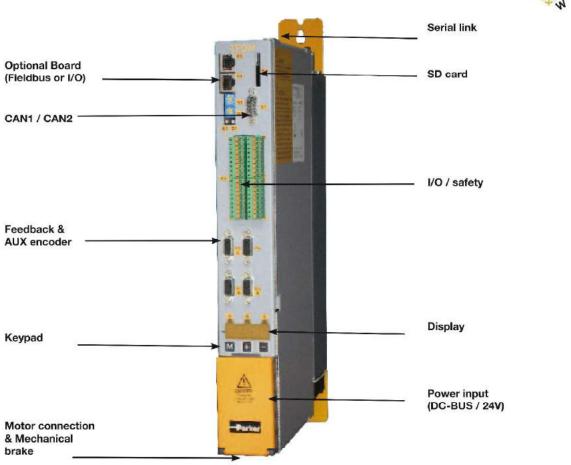
2006/95/EC	Low voltage directive
EN 60204-1	Safety of machinery - Electrical equipment of machines - Part 1: General requirements
EN 61800-5-1	Adjustable speed electrical power drive systems - safety requirements, thermal and energy
UL508C	(USA) Power Conversion Equipment
2004/108/EC	EMC directive
EN 61800-3	Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test method

### **Dimensions**

Туре	W [mm]	D [mm]	Weight [kg]
TPD-M 1/2/3 axes	50	270	4.3
TPD-M single axis 30 A	100	270	8.6
PSUP10	50	270	3.6
PSUP20 / PSUP30	100	270	5.4



### **Connector Layout**



## Accessories and Options

### Hiperface DSL® Feedback

### Description

The Single Cable Servo Drive System from Parker is a combination of the low inertia servo motor SME and the triple axis servo drive TPD-M based on the Hiperface DSL® digital feedback technology. The encoder feedback communication is fully integrated into the motor power cable and thus no separate feedback cable between drive and motor is required.

The new feedback system is a purely digital encoder communication protocol with exceptional performance. The absolute position determination, a resolution of up to 20 bit per turn, as well as 4096 maximum rotations, is unique in it's class.

The System is completed by the multi-axis servo drive TPD-M which represents one of the most compact solutions on the market giving the possibility of controlling up to three single cable SME servo motors with one 50 mm drive module.

Therefore, the Single Cable Servo Drive System from Parker is a bespoke solution to provide machine builders with lower cabling and installation cost and the possibility to reduce control panel size and machine footprint.

TPD-M triple axis servo drive connected to SME motors via Hiperface DSL® interface: One cable per servo motor instead of two.

### Feedback-Features

- One cable connection between drive and motor instead of two
- No need for separate feedback cable and connector
- Fully digital and interference-free communication
- · Synchronous, bidirectional, multi-channel
- · Easy setup and reduced wiring

### **Applications**

- Packaging Machinery
- Material Handling
- Machine Tools
- Robotics
- Paper & Converting

### Configuration Software - MotionWiz

MotionWiz is free of charge downloadable configuration software that allows users to configure and optimise the TPD-M series with a few easy clicks of the mouse.

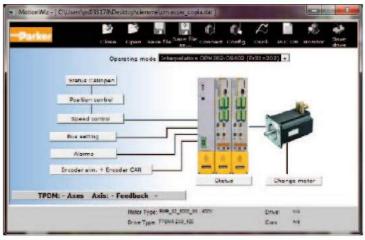
MotionWiz features an intuitive, easy and simple to use Windows® style environment to aid installation, optimisation and diagnostic use.

MotionWiz permits operation in both "on line" mode, directly in the controller, and in "offline" mode, remotely on the PC before downloading to the controller.

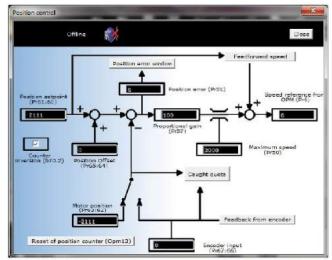
To simplify the configuration of systems with a large number of similar axes but with different motion profiles, MotionWiz allows users to copy the configuration from one application to another.

Inside the MotionWiz configurator is a database containing the technical characteristics of the full range of Parker motors and drives.

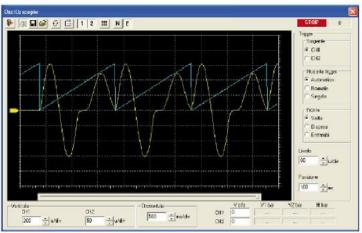
MotionWiz can be downloaded at www.parker.com/eme/tpdm



MotionWiz: General settings



MotionWiz: Position control



MotionWiz Oscilloscope: Real speed & torque trends

### **Order Code**

### TPD-M System

-		1	2	3	4	5	6	7
Ord	ler example	TPD	M	02 02 02		L	<b>E</b> 5	G
0.0								
1	<b>Drive Family</b>	v						
	TPD		Po	wer Drive				
2	Axes							
	М	Multi	Axis	3				
3	<b>Drive Size</b>							
	02 02 02	3 axi	s 2 /	A+2A+	2 A			
	08 05 05	3 axi	s 8 /	A+5A+	5 A			
	02 02	2 axi	s 2 /	A + 2 A				
	05 05	2 axi	s 5 /	A + 5 A				
	08 08	2 axi	s 8 /	A 8 + A				
	15 05	2 axi	s 15	A + 5 A				
	5	singl	e axi	s 5 A				
	10			s 10 A				
	15			s 15 A				
	30	singl	e axi	s 30 A				
4	Fieldbus							
	D	CAN	-	1				
5	Feedback s	TO CANADA CONTRACT						
	Empty field					^	0246400000000000	Telephones.
	E	- 50		ncrement	191			
	H			tal encod	er + H	ali se	nsors	
6	L Outing has		reea	back				
ь	Option boar		ntior					
	Empty field E5				oard			
	E7			option b expansio		d		
7	Accessories		Jylic	CAPAI ISIO	n boar	u		
_	G	Fixin	a sh	ield				
	w.	LIMIT	9 311	Ciu				

### Mains module: PSUP

Ord	er example	P30 P 10 D0 035 W100
1	<b>Device fam</b>	ily
	PSU	Power module
2	Device typ	
	Р	Power module
3	Nominal po	wer; supply voltage
	10 D6	10 kW; 400 VAC (3-phase)
	20 D6	20 kW; 400 VAC (3-phase)
	30 D6	30 kW; 400 VAC (3-phase) 1)
4	Interface	
	USB	USB connection
5	Options	
	M00	no additional supplement

3

4

5

LCG-0055-0.45 mH (WxDxH: 180 mmx140 mmx157 mm; 10 kg) LCG-0055-0.45 mH-UL (with UL certification) (WxDxH: 180 mmx170 mmx157 mm; 15 kg)

### Capacitor module

		1	2				
Order example		PSC	023 M00				
1	Accessorie	es					
	PSC	Capacitor module					
2	Туре						
	023 M00	23 µF no additiona	l supplement				
	047 M00	47 µF no additional supplement					
	068 M00	68 µF no additiona	I supplement				

#### Mains filter for PSUP

		1	2	
Order example		NFI	03/01	
1	Accessorie	es		
	NFI	Mains filter		
2	Туре			
	03/01	for PSUP10 Reference axis combi 6 x 10 m motor cable	nation 3 x 480 V 25 A length	
	03/02	for PSUP10 Reference axis combination 3 x 480 V 25 A 6 x 50 m motor cable length		
	03/03	for PSUP20, PSUP Reference axis combi 6 x 50 m motor cable	nation 3 x 480 V 50 A	

### **Braking resistors**

		1	2	
Order example		BRM	05/01	
1	Accessories			
	BRM	Braking resistor		
2	Туре			
	13/01	30 $\Omega$ / 0.5 kW <sub>cont.</sub> for PSUP10D6, for PSUP20D6 (2x30 $\Omega$ parallel)		
	14/01	15 $\Omega$ / 0.5 kW <sub>cont.</sub> for PSUP10D6 (2 x 15 $\Omega$ in series) for PSUP20, PSUP30		
	12/01	18 Ω / 4.5 kW <sub>cont.</sub> for PSUP30		

### Motor output choke

For disturbance suppression when the motor connecting cables are long.

er example	MDR	01/04	
Accessories			
MDR	Motor output choke (for TPD-M >20 m motor cable)		
Туре			
01/01	up to 16 A rated mo	otor current	
01/02	up to 30 A rated mo	otor current	
01/04	up to 6.3 A rated m	otor current	
	Accessorie MDR Type 01/01 01/02	Accessories  MDR Motor output choke (for TPD-M >20 m motor)  Type  01/01 up to 16 A rated motor)  01/02 up to 30 A rated motor)	

#### **Other Accessories**

Order Code	Description	
Motionwiz	Programming Software	
Exp-Ground	Fixing shield assembly	
USBTODRIVE	USB to RS232/422 converter with cable	

Operation of the PSUP30 only with line choke. Required line choke for the PSUP30: 0.45 mH / 55 A We offer the following line chokes: